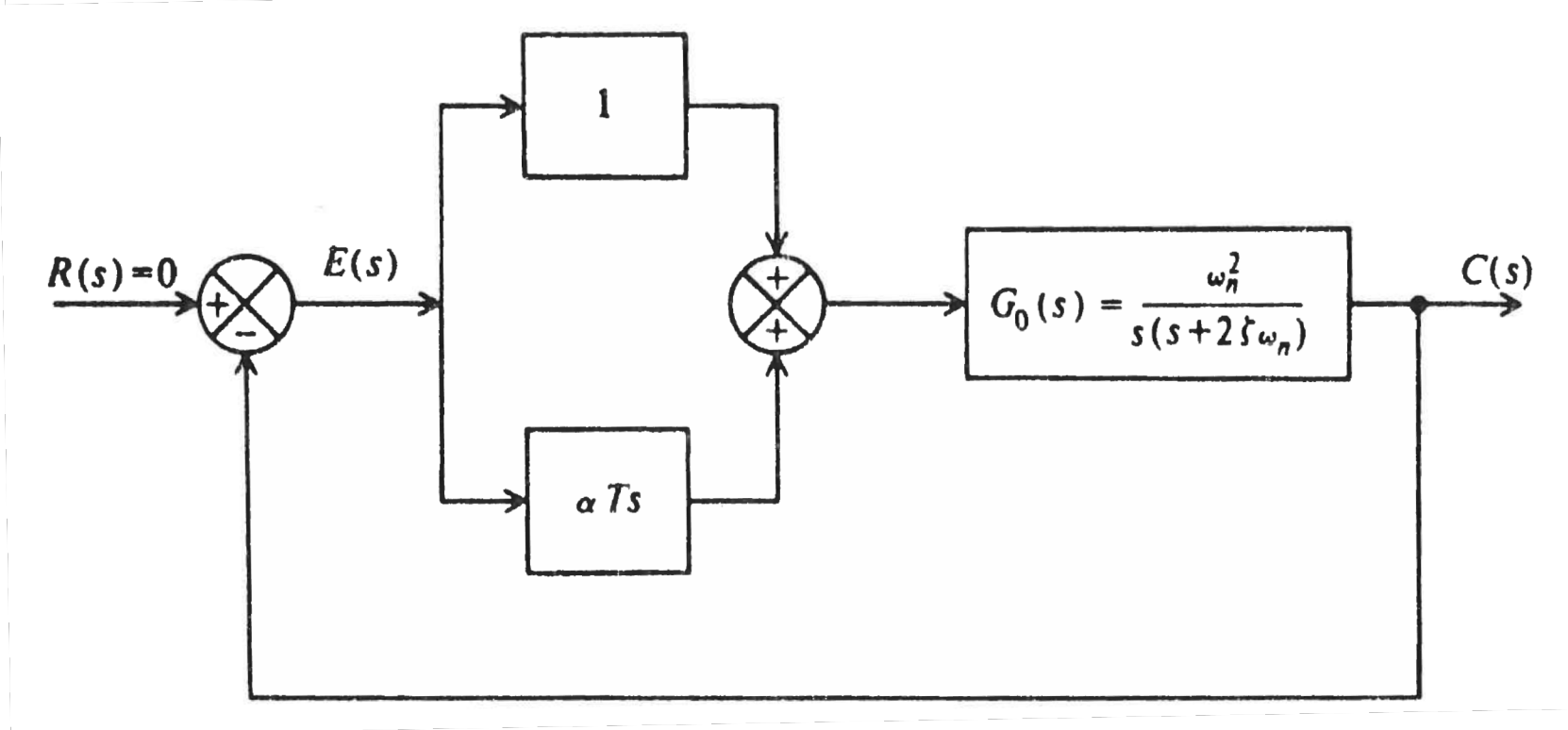
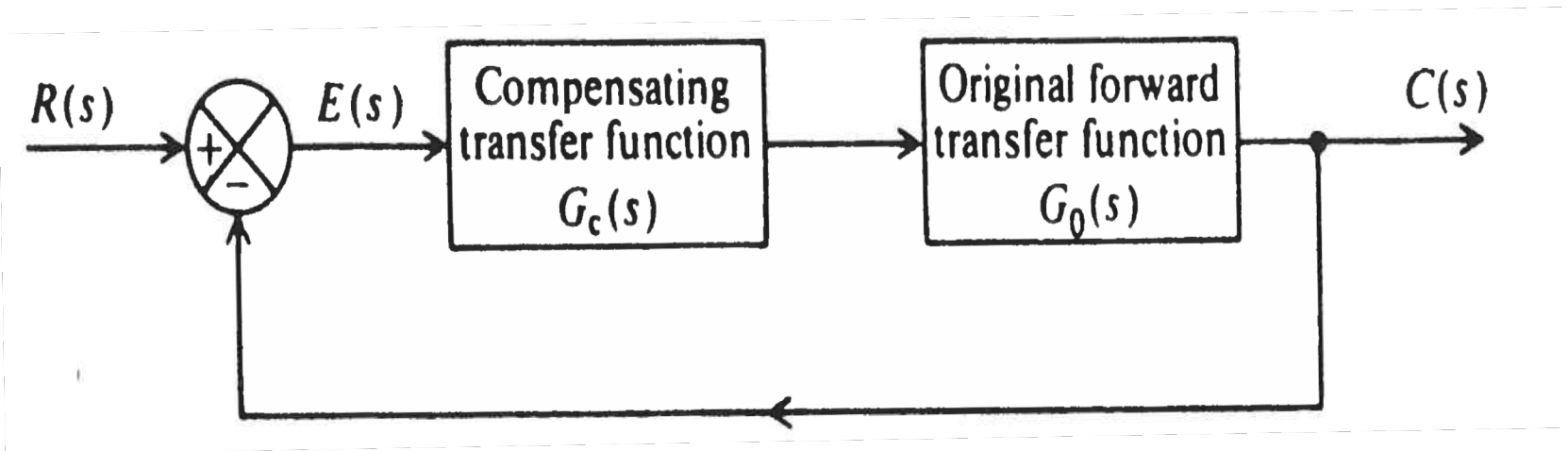


Cascade and Minor Loop

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Proportional plus derivative control

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1+G(s)} = \frac{\frac{\omega_n^2}{s(s+2\zeta\omega_n)}}{1+\frac{\omega_n^2}{s(s+2\zeta\omega_n)}}$$

$$= \frac{\omega_n^2}{s(s+2\zeta\omega_n)+\omega_n^2} = \frac{\omega_n^2}{s^2+(2\zeta\omega_n)s+\omega_n^2}$$

$$\frac{C(s)}{R(s)} = \frac{G(s)G_c(s)}{1+G(s)G_c(s)} \approx \frac{\frac{\omega_n^2(1+\alpha Ts)}{s(s+2\zeta\omega_n)}}{1+\frac{\omega_n^2(1+\alpha Ts)}{s(s+2\zeta\omega_n)}}$$

$$= \frac{\omega_n^2(1+\alpha Ts)}{s(s+2\zeta\omega_n)+\omega_n^2(1+\alpha Ts)} = \frac{\omega_n^2(1+\alpha Ts)}{s^2+(2\zeta\omega_n+\alpha T\omega_n^2)s+\omega_n^2}$$

$$(2\zeta\omega_n + \alpha T\omega_n^2) = 2\zeta_{eq}\omega_n$$

$$\zeta_{eq} = (2\zeta + \alpha T\omega_n) / 2 = \zeta + \alpha T\omega_n / 2$$

$$\begin{aligned}\frac{E(s)}{R(s)} &= \frac{1}{1+G(s)} = \frac{1}{1+\frac{\omega_n^2}{s(s+2\zeta\omega_n)}} \\ &= \frac{s(s+2\zeta\omega_n)}{s(s+2\zeta\omega_n)+\omega_n^2} = \frac{s(s+2\zeta\omega_n)}{s^2+(2\zeta\omega_n)s+\omega_n^2}\end{aligned}$$

$$R(s) = 1/s^2$$

$$E(s) = \frac{(s+2\zeta\omega_n)}{s(s^2+(2\zeta\omega_n)s+\omega_n^2)}$$

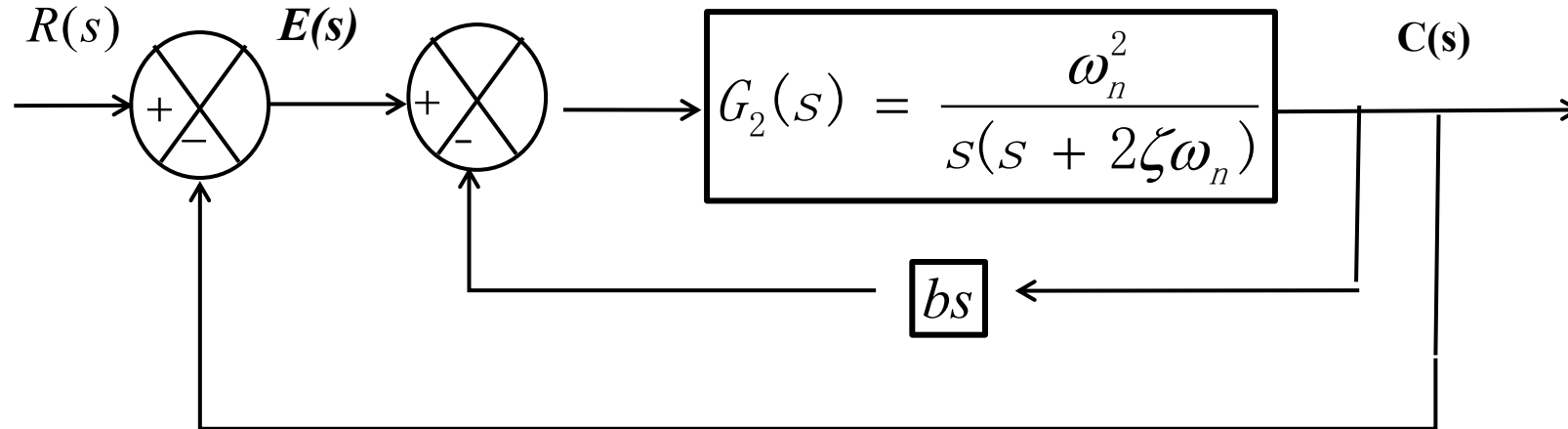
$$\begin{aligned}e_{ss(\text{ramp input})} &= \lim_{s \rightarrow 0} sE(s) \\ &= \lim_{s \rightarrow 0} s \frac{(s+2\zeta\omega_n)}{s(s^2+(2\zeta\omega_n)s+\omega_n^2)} \\ &= \frac{2\zeta\omega_n}{\omega_n^2} = \frac{2\zeta}{\omega_n}\end{aligned}$$

$$\begin{aligned}\frac{E(s)}{R(s)} &= \frac{1}{1+G(s)G_c(s)} = \frac{1}{1+\frac{\omega_n^2(1+\alpha Ts)}{s(s+2\zeta\omega_n)(1+Ts)}} \\ &= \frac{s(s+2\zeta\omega_n)(1+Ts)}{s(s+2\zeta\omega_n)(1+Ts)+\omega_n^2(1+\alpha Ts)}\end{aligned}$$

$$E(s) = \frac{(s+2\zeta\omega_n)(1+Ts)}{s(s(s+2\zeta\omega_n)(1+Ts)+\omega_n^2(1+\alpha Ts))}$$

$$\begin{aligned}e_{ss(\text{ramp input})} &= \lim_{s \rightarrow 0} sE(s) \\ &= \lim_{s \rightarrow 0} s \frac{(s+2\zeta\omega_n)(1+Ts)}{s(s(s+2\zeta\omega_n)(1+Ts)+\omega_n^2(1+\alpha Ts))} \\ &= \frac{2\zeta\omega_n}{\omega_n^2} = \frac{2\zeta}{\omega_n}\end{aligned}$$

Minor-loop Feedback Compensation



$$G(s) = \frac{\omega_n^2}{s(s + 2\zeta\omega_n)}$$

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + (2\xi\omega_n + \omega_n^2 bs) + \omega_n^2}$$

$$2\xi\omega_n + \omega_n^2 b = 2\xi_{eq}\omega_n$$

$$\xi_{eq} = \xi + \frac{\omega_n b}{2}$$

$$R(s) = 1 / s^2, \quad \text{unit ramp input}$$

$$E(s) = \frac{1}{s} \left(\frac{s + 2\xi\omega_n + b\omega_n^2}{s(s + 2\xi\omega_n + b\omega_n^2) + \omega_n^2} \right)$$

$$e_{ss(\text{ramp input})} = \lim_{s \rightarrow 0} sE(s) = \frac{2\xi\omega_n + b\omega_n^2}{\omega_n^2} = \frac{2\xi}{\omega_n} + b$$